# Mechanisms for a No-Regret Agent: Beyond the Common Prior



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Northwestern University AEA/ASSA Annual Meeting

January 3-5, 2021

For more details, see full paper (arxiv.org/abs/2009.05518).

A High-Level Agenda in Game Theory

Can we replace prior knowledge with models of learning?

Yes? No-regret assumptions can discipline agents' behavior.

- E.g. Foster and Vohra (1997)
- ► E.g. Nekipelov, Syrgkanis, and Tardos (2015)

No? No-regret algorithms can behave in bizarre ways.

► E.g. Braverman, Mao, Schneider, and Weinberg (2018).

Can models of learning be adapted to strategic interactions?

We focus on Stackelberg games of incomplete information.

- Includes contract design, Bayesian persuasion, delegation, etc.
- 1. Principal decides on a policy, e.g.
- 2. Agent responds to that policy, e.g.
- 3. Payoffs depend on hidden state, e.g.

These models usually require common prior belief about the state.

• E.g. 40% chance policeman is at donut shop.



# This Paper (2/2)

#### We replace common prior with adversarial online learning.

Adversarial = no assumptions on the sequence of states.



We design low-regret mechanisms for the principal.

- Under permissive assumptions on the agent's behavior.
- We refine no-regret to counterfactual calibration.
- Agent must fully & consistently exploit her information.

# Agent's Regret

#### **No-regret:**

▶ In hindsight, agent prefers her algorithm to any fixed action.

### Calibration (no-internal-regret):

No-regret with past behavior as context.

These restrictions do not rule out pathological behavior.

- The adversary can correlate agent's actions with sequence of states to make it appear as if agent has additional information.
- Informally, can think of an agent that has access to additional data or notices patterns that we missed.

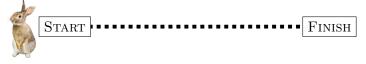
Tortoise travels 1km in 1h : uninformed agent satisfies no-regret.



Hare travels 1km in 1h : informed agent satisfies no-regret.



Hare travels 1km in 2min : informed agent satisfies no-regret conditioned on her information.



# Counterfactual Calibration

Information is revealed by the agent's on- and off-path behavior.

- On-path: agent's behavior under the principal's mechanism.
- Off-path: agent's behavior under counterfactual mechanisms.

#### **Counterfactual calibration:**

► No-regret with on- and off-path behavior as context.

Agent must fully & consistently exploit her revealed information.

# Online Mechanism Design

### **Principal's regret:**

- How much he prefers the best-in-hindsight fixed policy to his mechanism.
- Takes into account how changes to mechanism affect agent's behavior.
- Goal: design a mechanism that guarantees low principal's regret.
  - ► For any sequence of states.
  - ► For any counterfactually-calibrated behavior by the agent.

Ideally, we seek empirical analogs to the common prior policies.

# Main Results (1/2)

Reduce online problem to robust version of common prior problem.

Local robustness: agent nearly maximizes expected utility.

### Theorem (Informal)

Assume: agent's behavior is counterfactually calibrated.

Assume: agent isn't better informed than us (non-negative regret).

**Mechanism**: use the locally-robust policy, replacing the common prior with a calibrated forecast.

Result: principal's regret vanishes.

# Main Results (2/2)

Reduce online problem to robust version of common prior problem.

- Local robustness: agent nearly maximizes expected utility.
- Informational robustness: agent receives a private signal, but we do not know its quality.

### Theorem (Informal)

Assume: agent's behavior is counterfactually calibrated.

**Mechanism**: use the locally- and informationally-robust policy, replacing the common prior with a calibrated forecast.

**Result:** principal's regret  $\leq$  cost of informational robustness.

## Conclusion

### We replaced the common prior with online learning.

- ► For rich class of single-agent mechanism design problems.
- Counterfactual calibration  $\approx$  non-Bayesian rationality.
- If the agent reveals useful information on one path, she must also exploit it on other paths.

Many open problems, e.g.

- Extension to bandit feedback conceptually non-trivial!
- Mechanisms that learn about the agent's information.
- Computational tractability.

## Thank you!

For more details, see full paper (arxiv.org/abs/2009.05518).